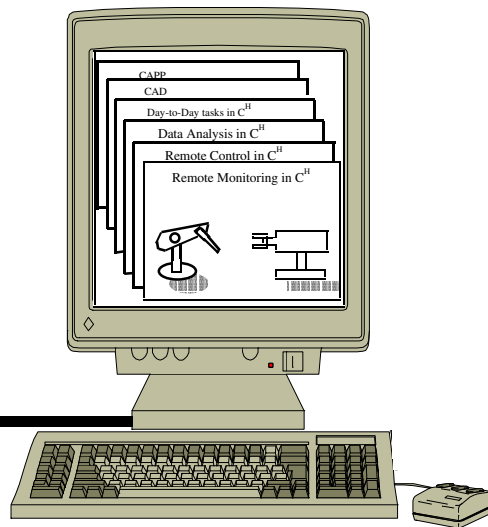


Board no.	VME Function
1	Motorola MVME 167 in C ⁺⁺ under real-time Unix LynxOS
2-3	8-axis servo control board PMAC-VME
4-5	8-axis servo control board PMAC-VME
6	I/O board
7	A/D board
8	JR3 force /torque receiver
9-10	MaxVideo 200
11	MaxScan
12	MaxScan

(Experimental Environment)

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(Remote Experimenter)



Ethernet